

# ANNEXES





Image : Symbiotic Leg



Image : Bras robotique DOF



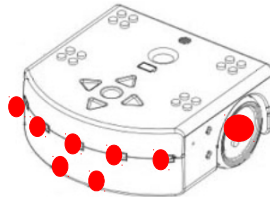
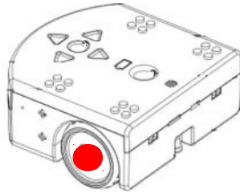
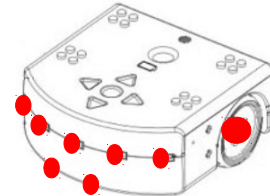
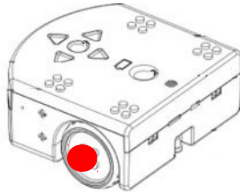
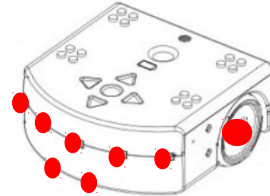
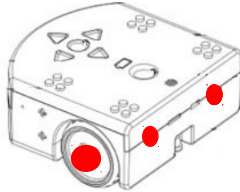
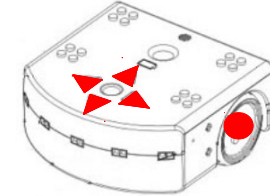
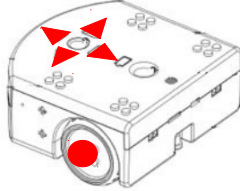




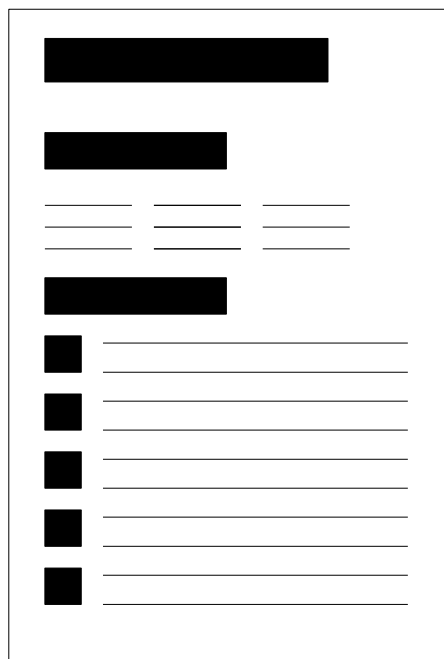
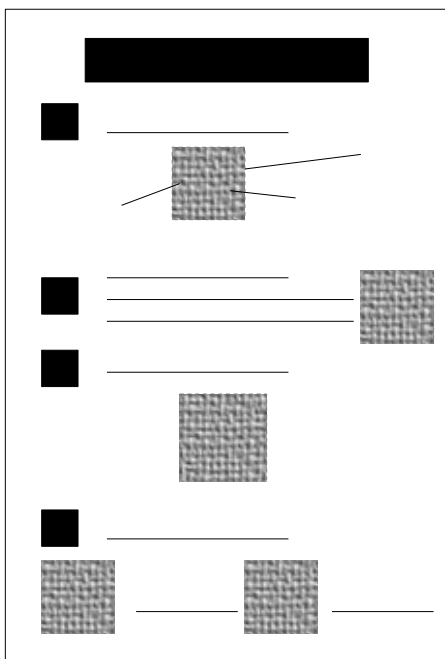
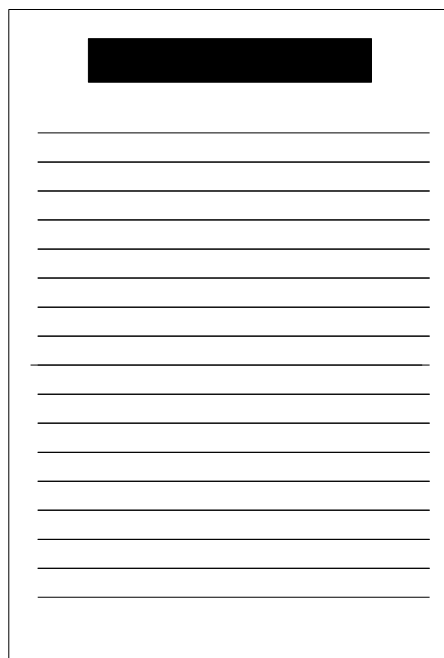
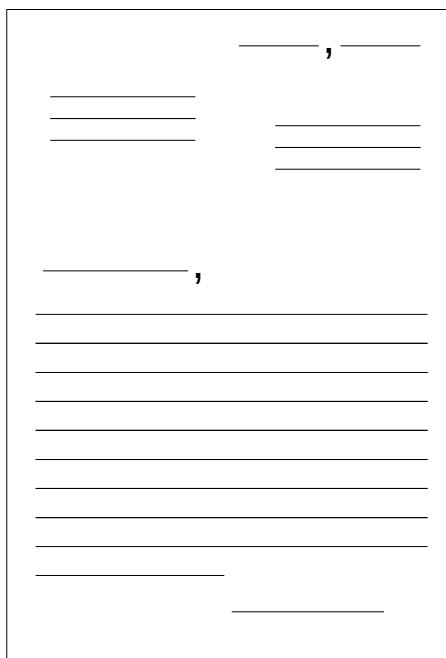
Image : Rover K-10 de la NASA



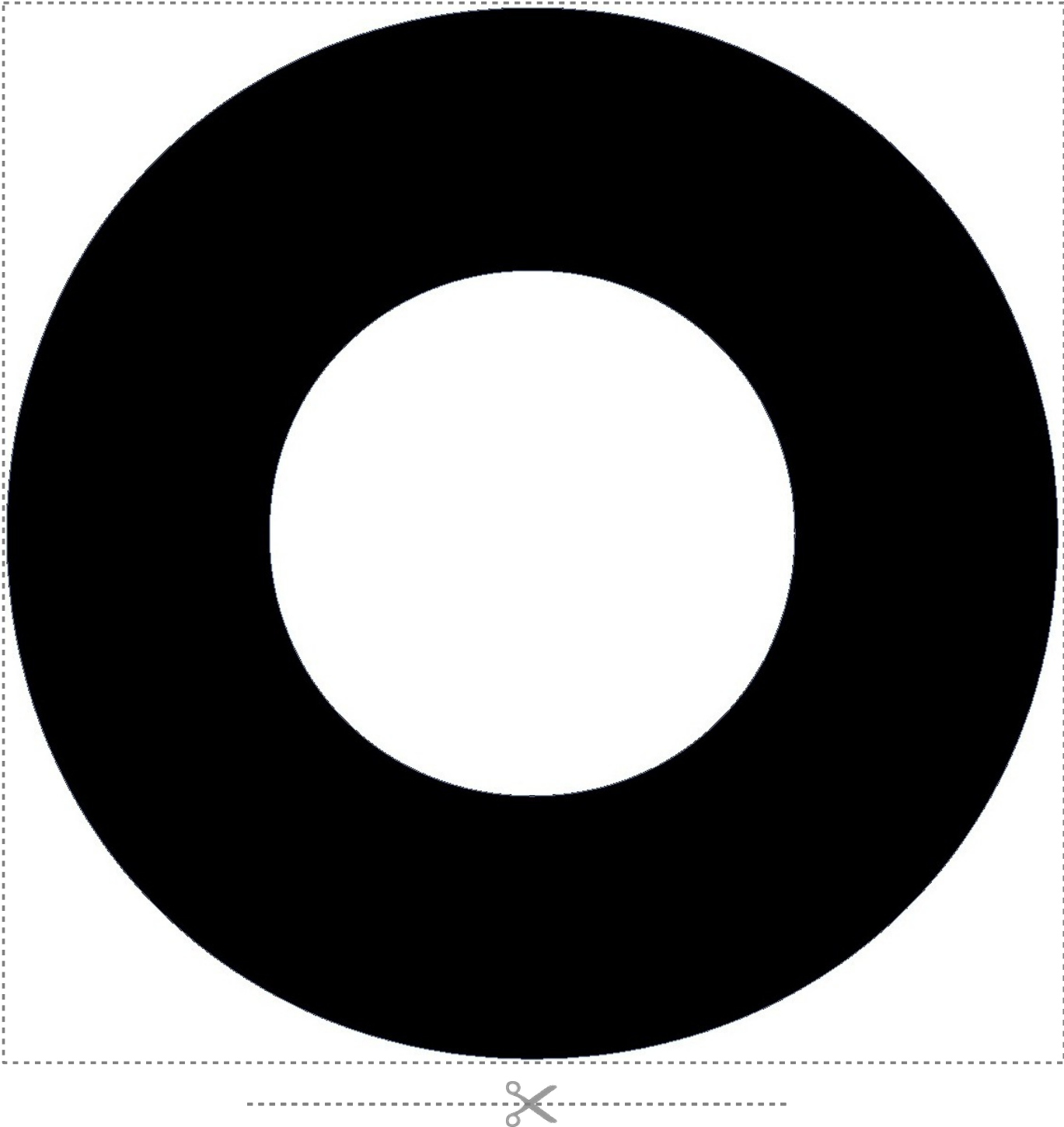


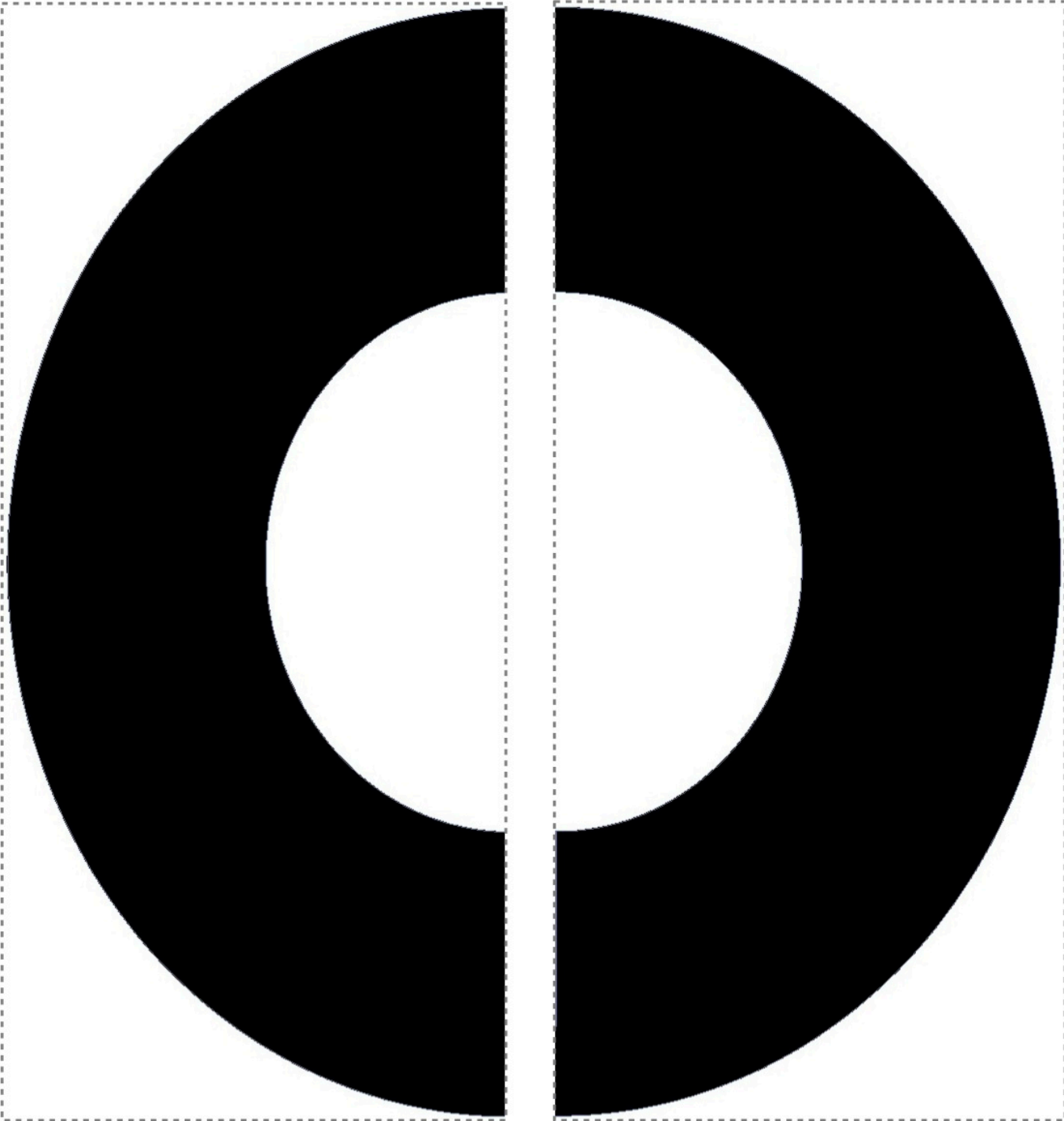
couleur	comportement observé	adjectif	éléments activés
<b>vert</b>	Il suit un objet proche de lui, tout en restant à une certaine distance. Il ne s'arrête que s'il détecte le vide (ou un sol noir).		 
<b>jaune</b>	Il explore son environnement tout en évitant les obstacles. Il ne s'arrête que s'il détecte le vide (ou un sol noir).		 
<b>rouge</b>	Il recule ou avance lorsqu'un obstacle s'approche à une certaine distance. Il ne s'arrête que s'il détecte le vide (ou un sol noir).		 
<b>violet</b>	Il obéit aux ordres donnés par les boutons (et la télécommande).		 

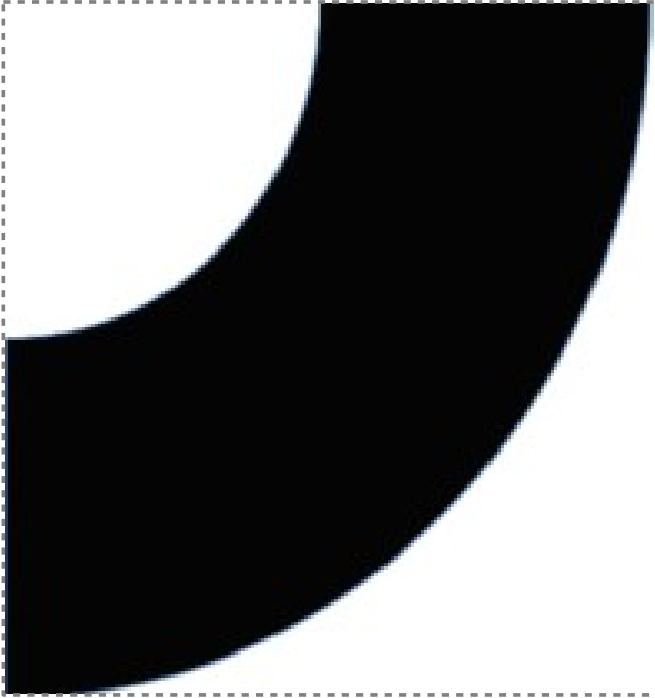
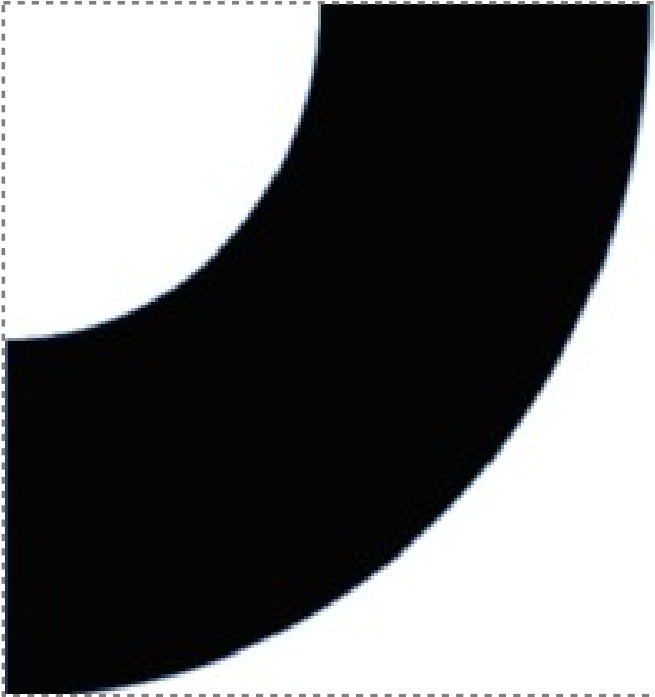
## Différents modèles de mise en page :

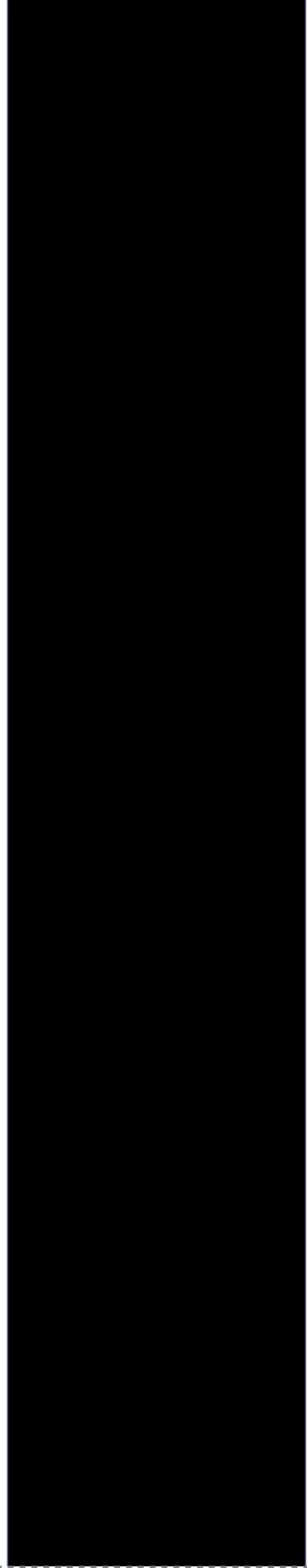
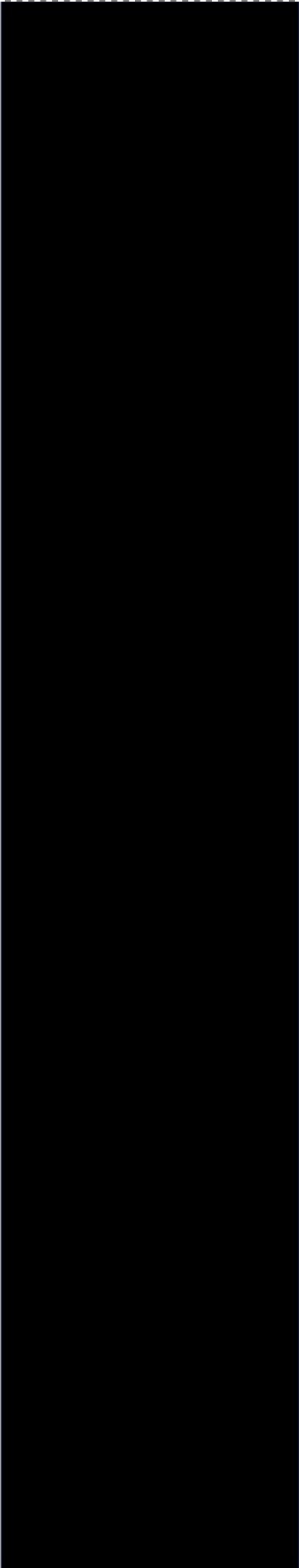


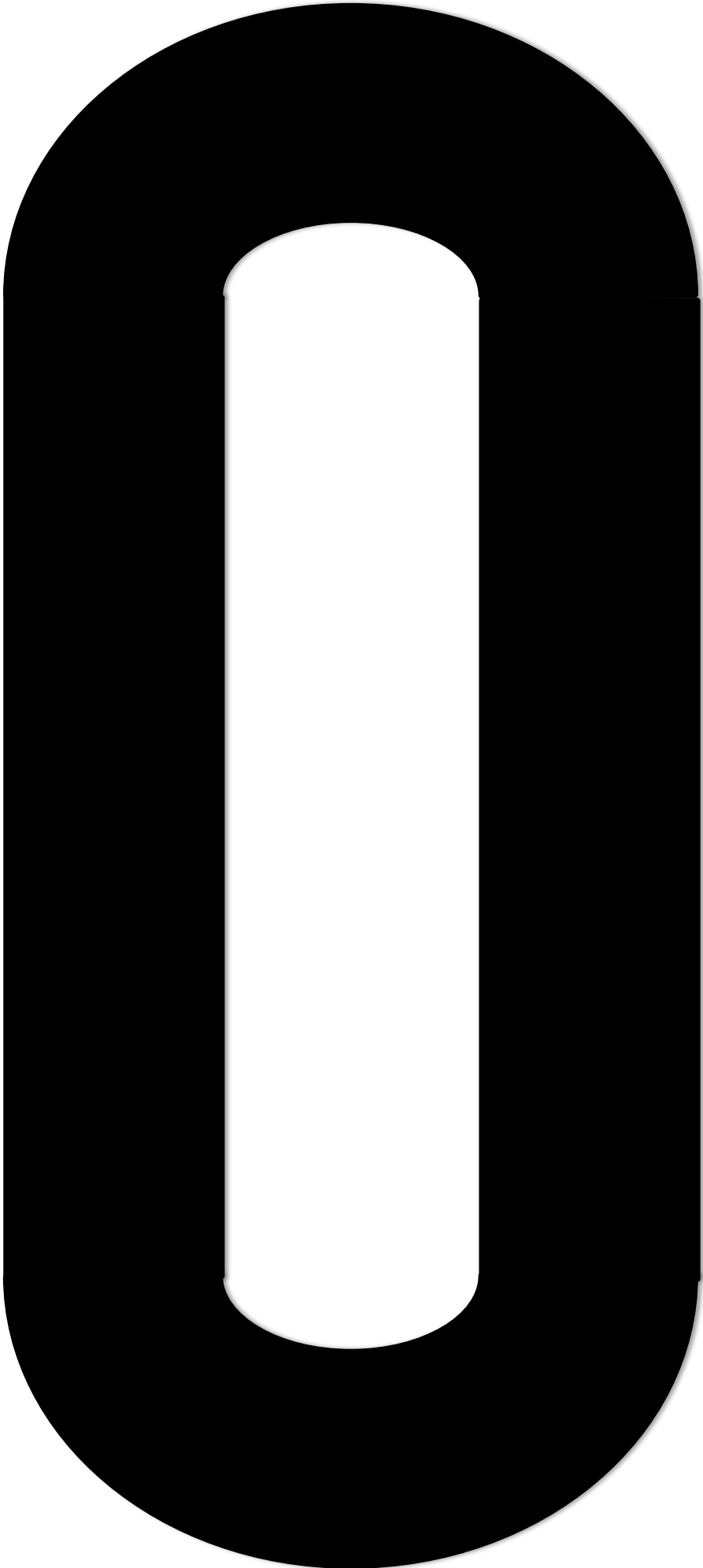
Piste pour défi n. 4 "Sur la route" p. 16







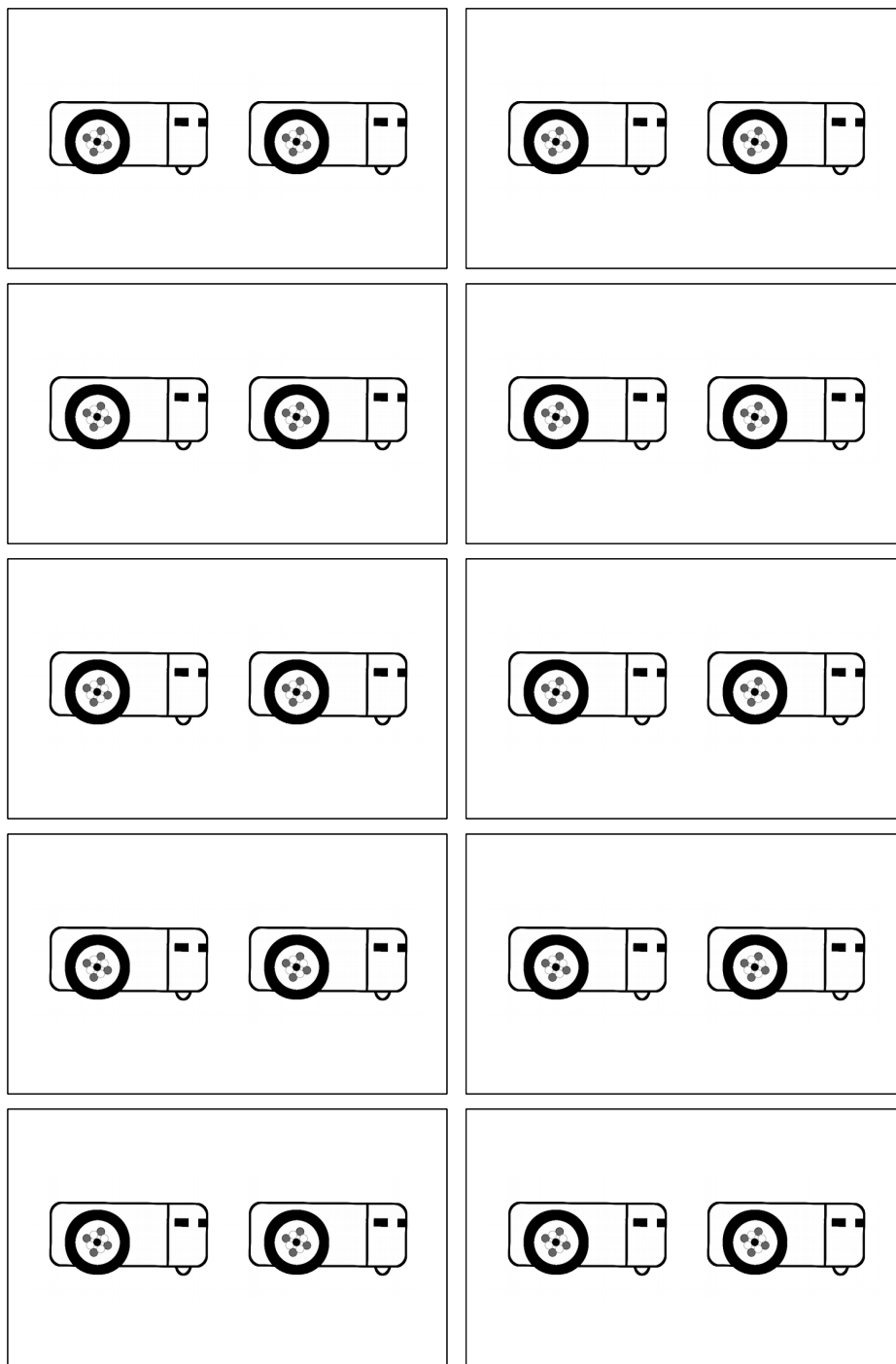






## "Duo de Thymio"

### Nos hypothèses :

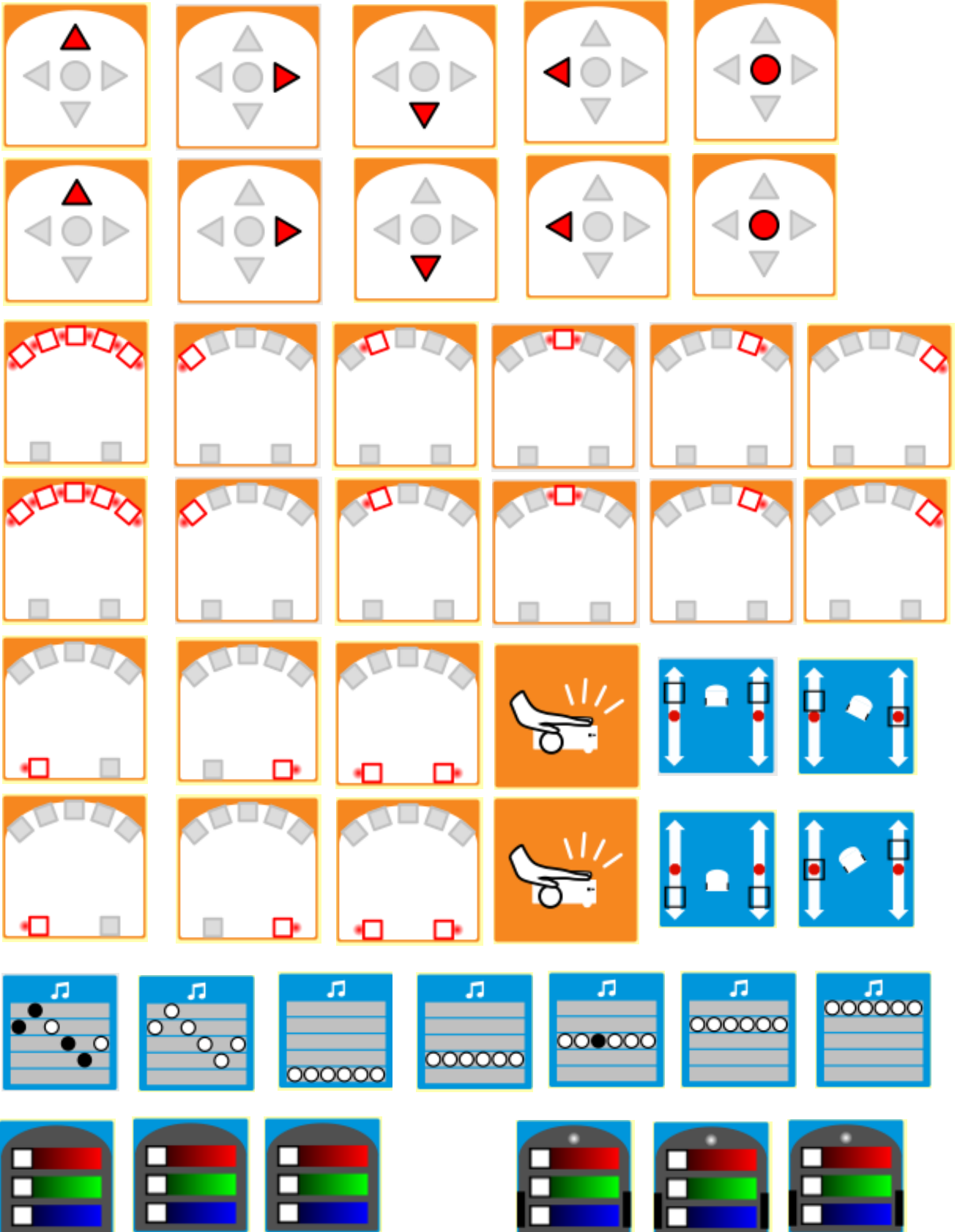
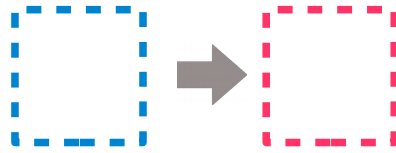


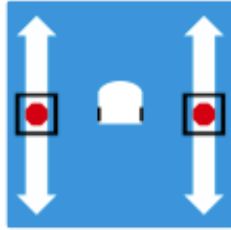


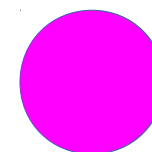
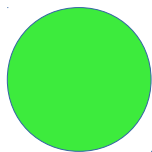
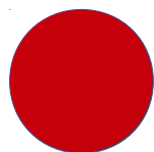
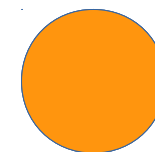
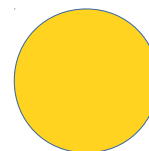
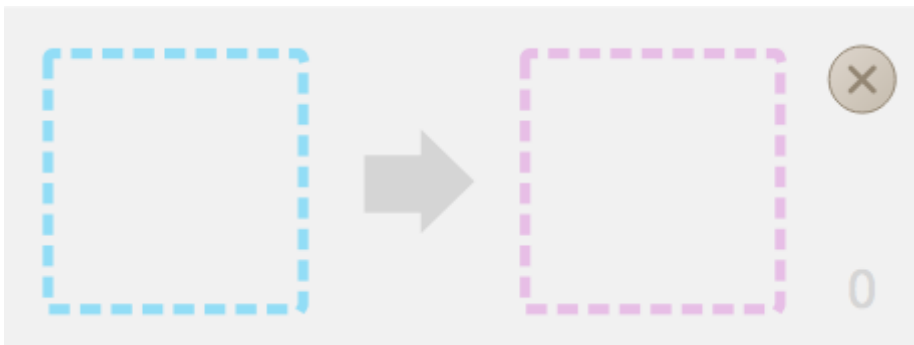
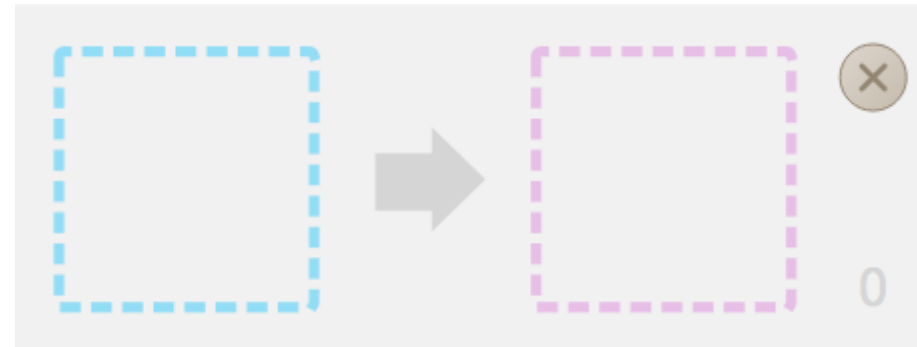
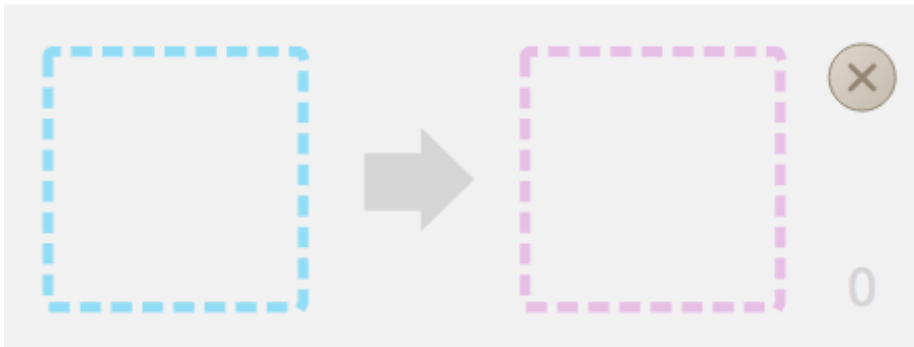


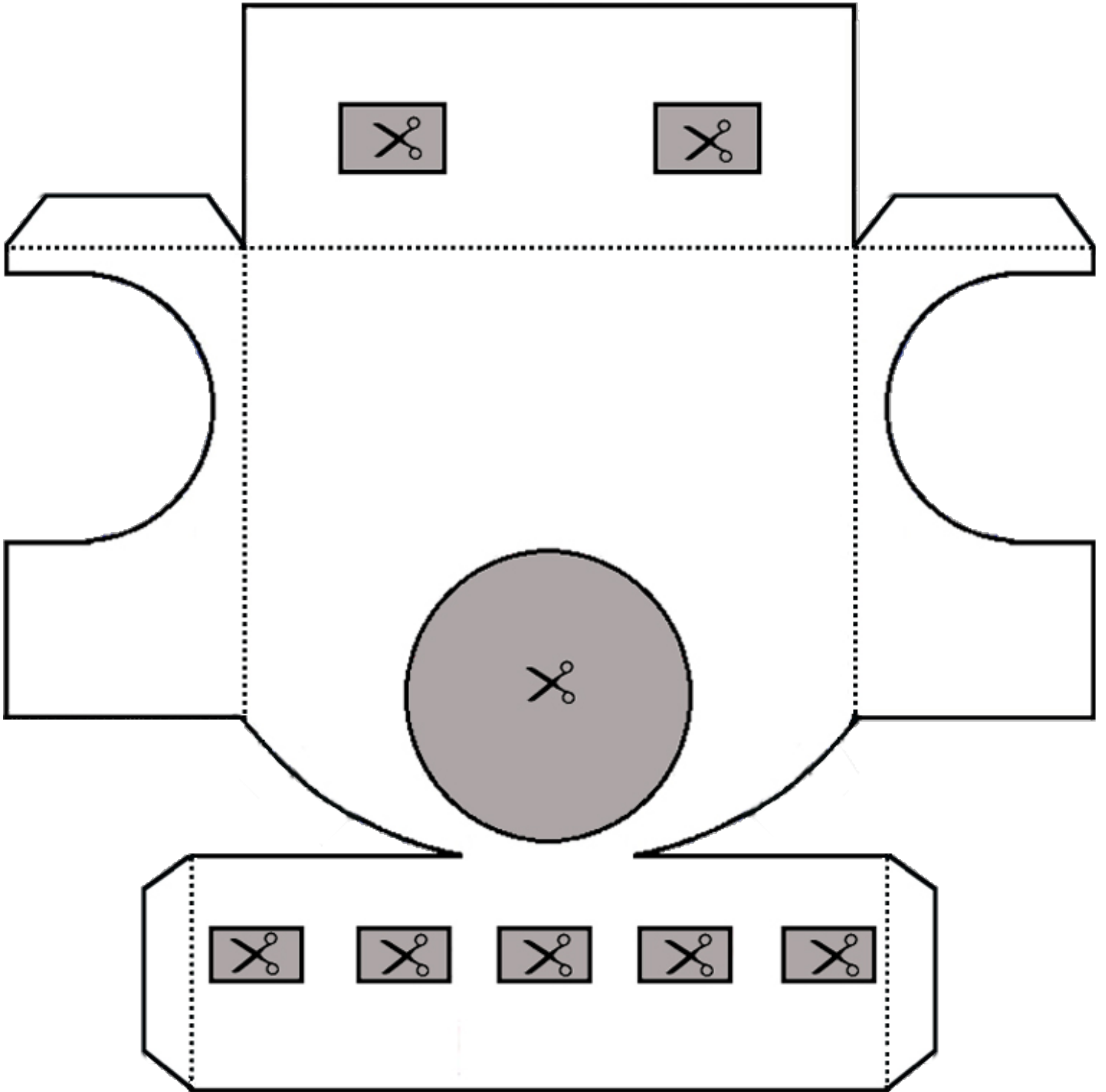
# "Prends les commandes"

Les pictos :

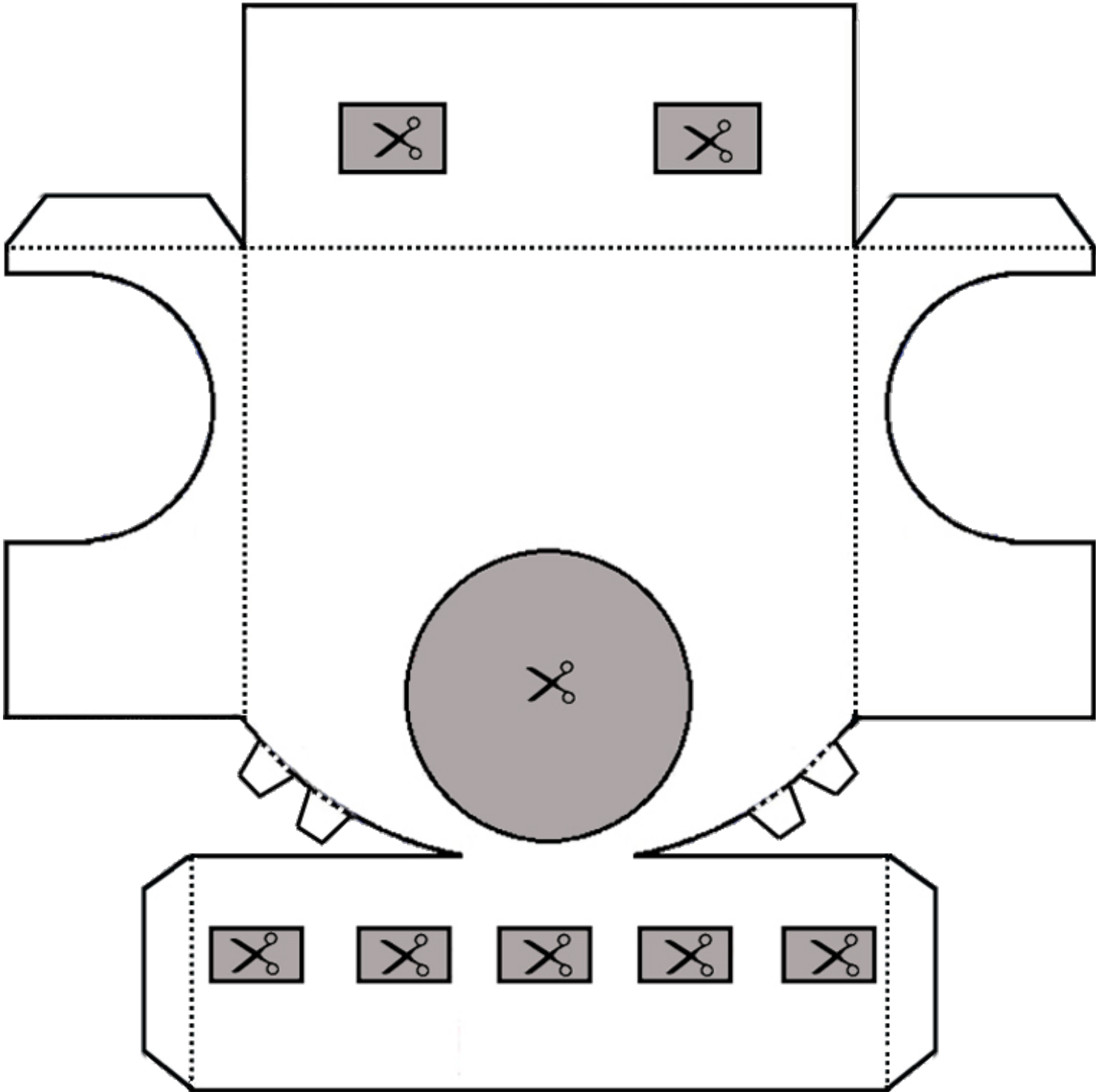








D'après les fiches de : T. Guitard, D. Roy, P-Y. Oudeyer, équipe Flowers (Inria, ENSTA ParisTech)



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